NTRODUCTION BACKGROUND MODEL PROPERTIES EMPIRICAL RESULTS CONCLUSIO

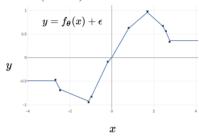
TOWARDS EXPRESSIVE PRIORS FOR BNNs: Poisson Process Radial Basis Function Networks

Melanie F. Pradier

Joint work with Beau Coker and Finale Doshi-Velez Harvard University

December 15th, 2019

NEURAL NETWORKS (NNs) AS UNIVERSAL APPROXIMATORS



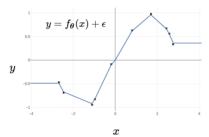
Several success stories...







BUT WHAT IF STAKES ARE HIGH?

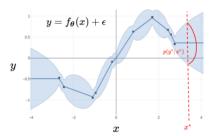








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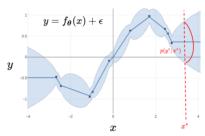








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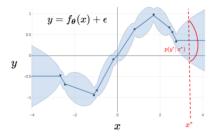
Uncertainty estimation becomes crucial!







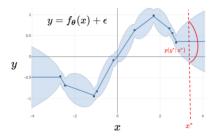
Sometimes we have a priori functional knowledge...



Some basic examples:

- ▶ Range of heart rate at rest between 60-100 bpm.
- ▶ Slow/fast variation of air pollutant
- ▶ Volatility of stock market

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How can we incorporate such functional desiderata into the model?

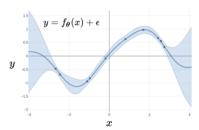
An easy way to specify functional desiderata: Gaussian Processes (GPs)

Definition: a Gaussian process is a collection of random variables, any finite number of which have (consistent) Gaussian distributions.

$$f \sim \mathcal{N} \big(\mu(\cdot), k\left(\cdot, \cdot\right) \big)$$

Example: RBF kernel as covariance function:

$$k(x, x') = \sigma^2 \exp\left(-\frac{(x - x')^2}{2\gamma^2}\right)$$



- ▶ Lengthscale
- ► Amplitude variance

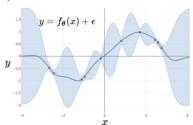
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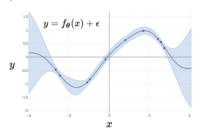
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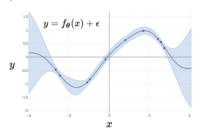
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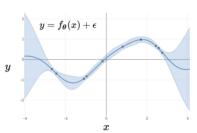
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- ► Amplitude variance

GPs are great, but what if I still want a NN?

Benefits of NN approaches:

- ▶ widely used (many tools available)
- ▶ parametric expression
- ▶ fast at evaluation time

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KEY RESEARCH QUESTIONS:

- 1. Can we design Bayesian NN priors that encode **stationarity properties** like a GP while retaining the benefits of neural networks?
- 2. Can we easily specify lengthscale and amplitude variance in a **decoupled** fashion?

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BACKGROUND

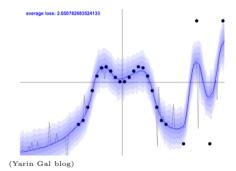
BAYESIAN NEURAL NETWORKS

- ► Assume prior on network parameters
- ▶ Most common, i.i.d Gaussians

$$\mathbf{y} = f_{\boldsymbol{\theta}}(\mathbf{x}) + \boldsymbol{\epsilon}$$

$$\boldsymbol{\epsilon} \sim \mathcal{N}(0, \sigma_y^2 I)$$

$$\theta_i \sim \mathcal{N}(0, \sigma_a^2 I) \quad \forall i$$



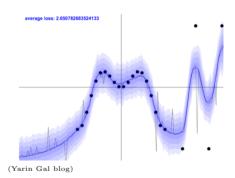
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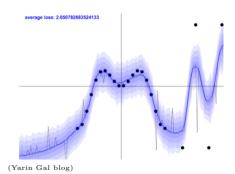
▶ But what does a prior over weights mean in function space?

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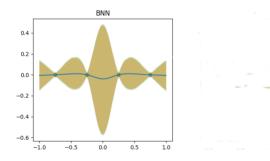
► But what does a prior over weights mean in function space?

Hard to know!

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NOT ONLY HARD TO ENCODE FUNCTIONAL PROPERTIES WITH BNNs; SOME PROPERTIES ARE IMPOSSIBLE TO GET

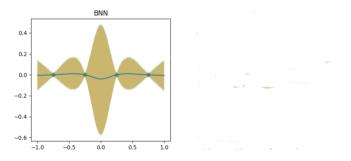
► For example, a BNN (with RBF activations) is nonstationary in amplitude variance (Williams, 1997)



RTRODUCTION BACKGROUND MODEL PROPERTIES EMPIRICAL RESULTS CONCLUSION

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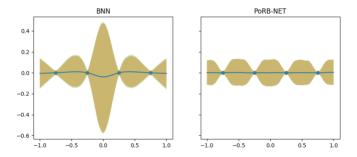


Question: can we design a Bayesian NN that exhibits stationarity?

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► For example, a BNN (with RBF activations) is nonstationary in amplitude variance (Williams, 1997)



Question: can we design a Bayesian NN that exhibits stationarity? Yes!

STRODUCTION BACKGROUND MODEL PROPERTIES EMPIRICAL RESULTS CONCLUSION

Related works

Expressive priors for Bayesian NNs

- ► Functional BNNs (Flam-Shepherd, et.al 2017; Sun et.al, 2019): sample-based optimization w.r.t. reference functional distribution
- ▶ Neural processes (Garnelo et al., 2018): meta-learning to identify functional properties based on many prior examples
- ▶ (Pearce et al., 2019) BNN architectures that recover equivalent GP kernel combinations in the infinite width limit

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	user specs	optim. free	finite width	deep
Sun et.al, 2019	yes	no	yes	yes
Garnelo et.al, 2018	no	no	yes	yes
Pearce et.al, 2019	yes	yes	no	yes
Porb-Net (this work)	yes	yes	yes	not yet

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RADIAL BASIS FUNCTION NETWORKS (RBFNs)

➤ Around since the 90s (Gyorfi et.al, 2002), recently renewed attention (Taghi et.al, 2004; Zadeh et.al, 2018)

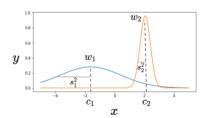
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RADIAL BASIS FUNCTION NETWORKS (RBFNS)

- ▶ Around since the 90s (Gyorfi et.al, 2002), recently renewed attention (Taghi et.al, 2004; Zadeh et.al, 2018)
- ▶ NN based on radial basis $\phi(\cdot)$, e.g., $\phi(x) = \exp(-x^2)$

$$f_{\boldsymbol{\theta}}(x) = b + \sum_{k=1}^{K} w_k \phi(s_k(x - c_k)),$$

- $\mathbf{s}_k^2 \in \mathbb{R}$: scale
- $c_k \in \mathbb{R}$: center
- $\triangleright w_k \in \mathbb{R}$: output weight
- $b \in \mathbb{R}$: output bias



BACKGROUND

Comparison RBFN versus BNN formulation (D=1)

$$f_{\boldsymbol{\theta}}(x) = b + \sum_{k=1}^{K} w_k \phi \left(s_k(x - c_k) \right)$$
 $f_{\boldsymbol{\theta}}(x) = b + \sum_{k=1}^{K} w_k \phi \left(v_k x + d_k \right)$

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Take-away: priors on different random quantities, RBFN more intuitive

BAYESIAN RBFNs (BARBER ET.AL, 1998)

$$c_k \sim \mathcal{N}(0, \sigma_c^2)$$

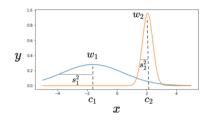
$$s_k^2 \sim \operatorname{Gamma}(\alpha_s, \beta_s)$$

$$w_k \sim \mathcal{N}(0, \sigma_w^2 I)$$

$$b \sim \mathcal{N}(0, \sigma_b^2)$$

$$y_n | x_n, \boldsymbol{\theta} \sim \mathcal{N}(f_{\boldsymbol{\theta}}(x_n), \sigma_y^2)$$

$$f_{\theta}(x) = b + \sum_{k=1}^{K} w_k \exp\left(-s_k^2 (x - c_k)^2\right)$$



- $ightharpoonup s_k^2 \in \mathbb{R}$: scale
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RODUCTION BACKGROUND

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AMBIDICAL DECITE

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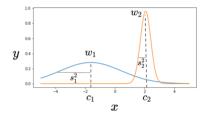
$$w_k \sim \mathcal{N}(0, \sigma_w^2 I)$$

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where

$$f_{\theta}(x) = b + \sum_{k=1}^{K} w_k \exp\left(-s_k^2 (x - c_k)^2\right)$$



- $ightharpoonup s_h^2 \in \mathbb{R}$: scale
- $c_k \in \mathbb{R}$: center
- \triangleright $w_k \in \mathbb{R}$: output weight
- ▶ $b \in \mathbb{R}$: output bias

Functional properties still hard or impossible to encode!

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FUNCTIONAL PROPERTIES STILL HARD OR IMPOSSIBLE

Issues:

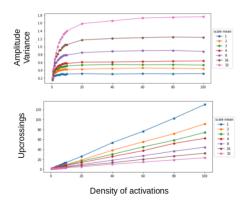
- ▶ non-stationary covariance function (Williams, 1997)
- ▶ lengthscale and variance are **coupled**

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FUNCTIONAL PROPERTIES STILL HARD OR IMPOSSIBLE

Issues:

- ▶ non-stationary covariance function (Williams, 1997)
- ▶ lengthscale and variance are **coupled**



- ➤ As RBFs concentrate in same region:
 - ▶ summation ⇒ higher variance
 - increase in expressivity⇒ more upcrossings

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Model

BACKCROUND

Poisson Process Radial Basis Function Networks (PoRB-NET)

$$c_k \sim \mathcal{N}(0, \sigma_c^2)$$

$$s_k^2 \sim \operatorname{Gamma}(\alpha_s, \beta_s)$$

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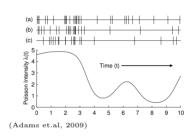
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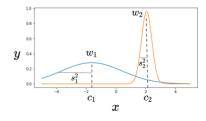
TRODUCTION BACKGROUND MODEL PROPERTIES EMPIRICAL RESULTS CONCLUSION

Poisson Process Radial Basis Function Networks (PoRB-NET)

$$\begin{array}{ccc} \mathbf{c} \mid \boldsymbol{\lambda} & \sim & \operatorname{Poisson Process} \left(\boldsymbol{\lambda} \right) \\ s_k^2 & \sim & \operatorname{Gamma}(\alpha_s, \beta_s) \\ w_k & \sim & \mathcal{N} \left(0, \tilde{\sigma}_w^2 I \right) \\ b & \sim & \mathcal{N}(0, \tilde{\sigma}_b^2) \\ y_n \mid x_n, \boldsymbol{\theta} & \sim & \mathcal{N}(f_{\boldsymbol{\theta}}(x_n), \sigma_y^2) \end{array}$$

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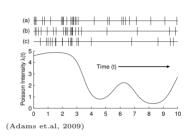


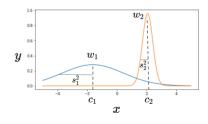
TRODUCTION BACKGROUND MODEL PROPERTIES EMPIRICAL RESULTS CONCLUSION

Poisson Process Radial Basis Function Networks (Porb-NET)

$$\begin{array}{rcl} \mathbf{c} \mid \lambda & \sim & \operatorname{Poisson Process} \left(\lambda \right) \\ s_k^2 & = & \lambda^2(c_k) \\ w_k & \sim & \mathcal{N} \left(0, \tilde{\sigma}_w^2 I \right) \\ b & \sim & \mathcal{N} (0, \tilde{\sigma}_b^2) \\ y_n \mid x_n, \boldsymbol{\theta} & \sim & \mathcal{N} (f_{\boldsymbol{\theta}}(x_n), \sigma_y^2) \end{array}$$

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STRODUCTION BACKGROUND MODEL PROPERTIES EMPIRICAL RESULTS CONCLUSION

WHAT IF WE DON'T KNOW THE INTENSITY FUNCTION?

STRODUCTION BACKGROUND MODEL PROPERTIES EMPIRICAL RESULTS CONCLUSION

WHAT IF WE DON'T KNOW THE INTENSITY FUNCTION?

Prior on Intensity Function of Poisson Process

$$h \sim \operatorname{GP}(0, C(\cdot, \cdot))$$

$$\lambda^* \sim \operatorname{Gamma}(\alpha_{\lambda}, \beta_{\lambda})$$

$$\lambda(c) = \lambda^* \operatorname{sigmoid}(h(c)),$$

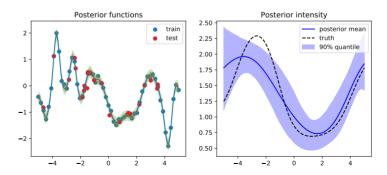
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INFERENCE

1. Update network parameters $\boldsymbol{\theta}$ given fixed nr. of hidden units K via Hamiltonian Monte Carlo (HMC)

$$p(\boldsymbol{\theta} | \mathbf{y}, \mathbf{x}, K, \lambda) \propto \left(\prod_{n=1}^{N} \mathcal{N}(y_n; f(x_n; \boldsymbol{\theta})) \right) \mathcal{N}(b; 0, \sigma_b^2) \left(\prod_{k=1}^{K} \mathcal{N}(w_k; 0, \sigma_w^2) \lambda(c_k) \right)$$

- 2. Update network width K via birth/death moves
- 3. Update point-estimate for Poisson process intensity λ

$$\hat{\lambda}(c) \approx \frac{1}{S} \sum \lambda^* \phi(h^{(s)}(c)),$$

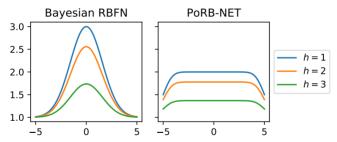
where $h^{(s)} \sim p(h|\mathbf{y}, \mathbf{x}, \boldsymbol{\theta})$.

PROPERTIES

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STATIONARITY

$$Cov(f(x), f(x+h)) = \sigma_b^2 + \sigma_w^2 \mathbb{E}[K] \underbrace{\mathbb{E}_{\theta} \left[\rho(x; \theta) \rho(x+h; \theta) \right]}_{:=U(x, x+h)}$$



$$U(x_1,x_2) \propto \underbrace{\exp\left(-\frac{(x_1-x_2)^2}{2(2\sigma_s^2+\sigma_s^4/\sigma_c^2)}\right)}_{Stationary} \underbrace{\exp\left(-\frac{x_1^2+x_2^2}{2(2\sigma_c^2+\sigma_s^2)}\right)}_{Nonstationary}$$

$$U(x_1, x_2) = \frac{\lambda}{\Lambda} \sqrt{\frac{\pi}{s^2}} \exp\left\{ -s^2 \left(\frac{x_1 - x_2}{2} \right)^2 \right\}$$
$$\left[\Phi((C_1 - x_m)\sqrt{2s^2}) - \Phi((C_0 - x_m)\sqrt{2s^2}\lambda) \right]$$

ODUCTION BACKGROUND

DECOUPLED LENGTHSCALE AND AMPLITUDE VARIANCE

► Homogeneous Poisson Process

- ▶ We derive closed-form expression for covariance function
- ightharpoonup Poisson process defined over finite region $\mathcal C$
- ightharpoonup As size of \mathcal{C} tends to infinity,

$$\operatorname{Cov}(f(x_1), f(x_2)) \approx \sigma_b^2 + \tilde{\sigma}_w^2 \exp\left\{-\lambda^2 \left(\frac{x_1 - x_2}{2}\right)^2\right\}$$

▶ Non-homogeneous Poisson Process

▶ Empirical stationarity

RODUCTION BACKGROUND MODEL PROPERTIES EMPIRICAL RESULTS CONC.

Consistency

▶ Estimator $\hat{g}_n(x)$ is said to be consistent with respect to the true regression function $g_0(x)$ if, as n tends to infinity:

$$\int (\hat{g}_n(x) - g_0(x))^2 dx \xrightarrow{p} 0.$$

▶ Posterior consistent over Hellinger neighborhoods if $\forall \epsilon > 0$,

$$p(\lbrace f: D_H(f, f_0) \leq \epsilon \rbrace) \xrightarrow{p} 1.$$

▶ (Lee,2000) shows that Hellinger consistency implies frequentist consistency.

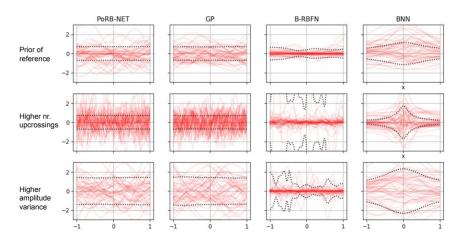
THEOREM (CONSISTENCY OF PORB-NETS)

A PoRB-NET with uniform intensity function is Hellinger consistent as the number of observations goes to infinity. STRODUCTION BACKGROUND MODEL PROPERTIES EMPIRICAL RESULTS CONCLUSION

EMPIRICAL RESULTS

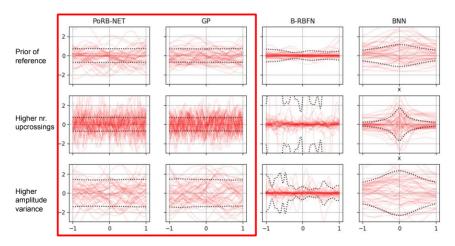
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PORB-NET ALLOWS FOR EASY SPECIFICATION OF LENGTHSCALE AND SIGNAL VARIANCE LIKE A GP



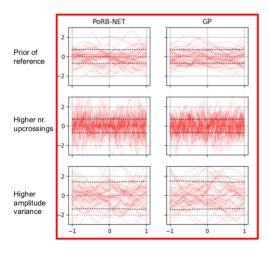
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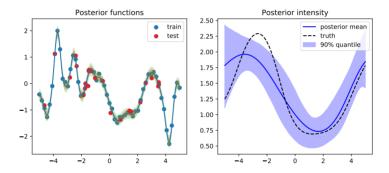
PORB-NET ALLOWS FOR EASY SPECIFICATION OF LENGTHSCALE AND SIGNAL VARIANCE LIKE A GP



- 1. stationarity
- 2. easy specification in a decoupled manner

PRODUCTION BACKGROUND MODEL PROPERTIES EMPIRICAL RESULTS CONCLUSION

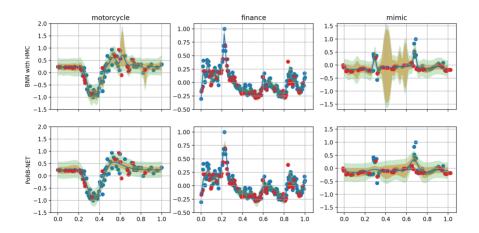
PORB-NET IS ABLE TO LEARN INPUT-DEPENDENT LENGTHSCALE INFORMATION



PoRB-NET adds more hidden units wherever needed, and adapts architecture width based on the data.

TRODUCTION BACKGROUND MODEL PROPERTIES EMPIRICAL RESULTS CONCLUSION

PORB-NET IS ABLE TO CAPTURE NON-STATIONARY PATTERNS IN REAL SCENARIOS, ADAPTING THE LENGTHSCALE LOCALLY



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CONCLUSION

STRODUCTION BACKGROUND MODEL PROPERTIES EMPIRICAL RESULTS CONCLUSION

CONCLUSION

In this talk, we have...

- ▶ highlighted incapacity of BNNs to express functional properties
- ▶ introduced PoRB-NET, a Bayesian NN prior to encode functional desiderata like a GP
- ▶ proposed an inference scheme to learn input-dependent lengthscale
- ▶ showed theoretical properties: (i) consistency, (ii) decoupling of amplitude and lengthscale
- validated empirically in synthetic and real datasets

All information online: https://arxiv.org/abs/1912.05779

NTRODUCTION BACKGROUND MODEL PROPERTIES EMPIRICAL RESULTS CONCLUSION

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In this talk, we have...

- ▶ highlighted incapacity of BNNs to express functional properties
- ▶ introduced PoRB-NET, a Bayesian NN prior to encode functional desiderata like a GP
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As future work: deeper networks, higher dimensions.

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Thank you for listening!

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COMPARISON RBFN VERSUS BNN FORMULATION (D=1)

$$f_{m{ heta}}(x) = b + \sum_{k=1}^{K} w_k \phi ig(s_k(x - c_k) ig)$$
 $f_{m{ heta}}(x) = b + \sum_{k=1}^{K} w_k \phi ig(v_k x + b_k ig)$ $s_k^2 \sim \operatorname{Gamma}(\alpha_s, \beta_s)$ $v_k^2 \sim \mathcal{N}(0, \sigma_v^2)$ $s_k \sim \mathcal{N}(0, \sigma_v^2)$ $s_k \sim \mathcal{N}(0, \sigma_v^2)$

Take-away: priors on different random quantities, RBFN more intuitive